

The CMS silicon tracker & performance



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Current and future tracking and vertexing detectors 2023 07.11.2023

Data taking conditions

- Luminosity delivered to CMS
 - \circ Run 1 + Run 2 is ~ 192 fb⁻¹
 - Run 1 + Run 2 + Run 3(till 2023) is 265 fb⁻¹





- In Run 3, mean number of interactions per bunch crossing > 46
 - ~ 37 in 2017/2018
- LHC now stable ~ 2.1 x 10³⁴ cm⁻² s⁻¹
- CMS running at L1 trigger rate ~ 110 kHz.

Charged particle tracking



#PV - 39

- Hits from different layers used to build particle trajectories.
- Intersection of different trajectories correspond to either collision points (primary vertices) or displaced decays of long-lived particles (secondary vertices). Need good spatial resolution to separate different vertices
- #vertices can go up to ~50 (Run 3) or more

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#PV - 55

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CMS Detector



CMS Silicon Tracker











CMS Tracker - Pixels



- Closest to the interaction point. Particle-hit rate up to 600MHz/cm² (Layer 1)
- Installed in end of year 2016- early 2017
- 1856 modules, ~124M channels, (100 × 150μm²)
- 4 hit coverage up to |η| = 3
- Barrel Pixel (**BPix**): 4 layers
- Forward Pixel (**FPix**): 3 disks arranged in 2 rings
- Refurbishment during the long shutdown after end of Run 2
- Completely new BPix Layer 1 installed in 2022
 - New front-end readout chip to be able to cope with higher rates
 - can operate upto 800 V (600 V during Run 2)

Pixel modules





- Silicon sensor sandwiched between between high-density interconnect (HDI) flex printed circuit and 16 readout chips (ROC) organized in 2×8 matrix
- ROCs bump-bonded to sensor and wire-bonded to HDI
 - PSI46dig ROC in BPix L2-L4 and FPix
 - $\circ \quad \mathsf{PROC600}\,\mathsf{ROC}\,\mathsf{in}\,\mathsf{BPix}\,\mathsf{L1}$
- HDI contains Token Bit Manager (TBM) chip (2 in case of L1) that coordinates the readout of ROCs.
- Silicon sensor: n⁺-in-n type, 285 µm thick, 16.2×64.8 mm² active area.

Pixel performance - Cluster charge



- Cluster charge on-track for BPix and FPix
 - \circ Clusters are required to be attached to the tracks with p_{T} > 1 GeV
 - Radiation damage introduces the charge efficiency loss which is recovered by raising the HV.
- Regular bias scans are done during data taking to determine the best operating point of the detectors in various layers (more crucial for Layer 1).
- Current HV settings
 - \circ $\hfill BPix$ Layer 1: 450V, Layer 2: 350V, Layer 3 & 4: 250V
 - FPix Ring 1: 350V, Ring 2: 300V

Pixel performance - Cluster charge trend



- Evolution of on-track cluster charge in BPix/FPix vs integrated lumi in Run 3
- Trend shows degradation of performance due to irradiation esp in the BPix L1 which is ~ 3 cm away from beam-pipe
 - \circ \qquad Mitigate by raising HV and updating Lorentz Angle

Pixel performance - Hit Efficiency

- Hit efficiency the probability to find any cluster within 1mm around an expected hit
 - measured with muon tracks
 - bad components are excluded.
- At instantaneous lumi of ~ 2 E 34 cm⁻² s⁻¹
 - **BPix L1** can operate at > **96%** hit efficiency
 - BPIX L2-4 and FPIX > 98% hit efficiency



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0.2 _300

-200

-100

-100 0 100 200 30 Residuals z direction (μm) 300 14

Strip tracker





- Active area 200 m², 5.6 m long, 2.5 m diameter with 15148 silicon modules (p-in-n sensors), 9.6 million electronic channels.
- 10 layers in barrel region, 4 Inner Barrel (TIB), 6 Outer Barrel (TOB).
- 3+9 discs in the inner disks (TID) and endcaps (TEC)
- Stereo modules (two modules with 100 mrad stereo angle) in 4 layers in barrel & 3 rings in endcap. → 2D hits from 1D strips
- 320 μm Si in inner layers (TIB, TID, TEC ring 1-4), 500 μm Si in outer layers (TOB, TEC ring 5-7)
- Analog readout.



Readout Strip modules

- Analogue readout with APV25 chip.
- Each chip has 128 channels.
- Tracker module have 4 or 6 APV chips.
- Two modes of operation:-
 - Peak mode single sample corresponds to the peak voltage of the signal.
 - Deconvolution mode three-sample weighted sum.
- Signal from 2 chips multiplexed to a Laser Driver.
- Signal from APV25 chips converted to optical signal on Analog-opto-hybrid (AOH).



$\mathsf{FED} \to \mathsf{Front} \ \mathsf{End} \ \mathsf{Driver}$

Strips - Silicon temperature



- Detector is currently operated at -22°C (since June 2023)
- Grey regions = modules excluded from data-taking
- Purple regions = modules with DCU data missing

Strips - Good detector fraction in Run 3



- Knowledge of bad components crucial for tracking
- Fraction of active channels during Run 3 ~ 96 %
 - Similar to Run 2.

Strips - Evolution of bad components in Run 3



- Knowledge of bad components crucial for tracking
- Fraction of active channels during Run 3 ~ 96 %
 - Similar to Run 2.
- The drop in TEC is related to recovery of uncooled modules

Strips - Signal over Noise



- Signal Over Noise for a run taken in 2023 (left)
- High S/N means better zero suppression and cluster building.
- As expected, a decrease is observed with time (center).
- Expected S/N ratio at the end of Run 3 (~500/fb).
 - Thin sensor 14.5
 - Thick sensor 18.5.

Strips - Hit efficiency



- Hit efficiency vs instantaneous
- Data used from a normal/very high lumi fills to compute hit efficiency..
- Hit Efficiency in
 - TOB: > 97. 5%, TIB: > 98. 5%
- Run 2 eff at **1.8** E 34 cm⁻² s⁻¹
 - TOB: > 98%, TIB: > 99%

Tracking performance



- Efficiencies are calculated using the tag-and-probe method exploiting the Z -> µµ decays
- Data used from early Run 3. Excellent tracking performance is observed.
- Efficiency is stable as a function of muon η (left) & number of primary vertices (right)

Conclusion

- The CMS Tracker operational since the beginning of Run 3 and took part in all periods of pp collision data taking
- Detector in good condition
 - Continuous monitoring
 - Calibrations
- Successful performance in data collection with proton-proton collisions with inst. lumi up to 2.1 x 10³⁴ cm⁻²s⁻¹, L1 trigger rate ~ 110 kHz.

Backup

Alignment





Alignment

- Main aim determine with enough precision the position and orientation of tracker modules such that the **alignment precision ~ intrinsic hit resolution** (~10 µm).
 - Minimization of track-hit residuals
- Automated alignment prompt alignment
 - Continuous monitoring of tracker high level structures
 - System in place to correct the geometry as soon as movement increases above certain thresholds
 - Similar precision (compared to offline) can be achieved in a short amount of time (put plot in backup)
- Offline alignment
 - track-based alignment run offline for refinement of online calibration,
 - o uses increased track kinematic variety and statistics
 - Higher granularity



Alignment observables



Median residual in X - The width of this distribution of the median of residuals (DMR) constitutes a measure of the local precision of the alignment results - deviations from zero indicate possible biases.



PV are first refitted removing the track under scrutiny Performance improves with higher statistics

- **Primary vertex validation** distributions of track-vertex residuals (impact parameters)
- Indicates possible bias in Pixel
- Perfect alignment around 0.

Alignment - trends



- **Black**: automated (online) Low Granularity alignment (high level structures)
- Red: refined offline + High Granularity automated alignment (last 2 fb⁻¹ before Technical stop)
- Blue: High Granularity alignment for remaining 30 fb⁻¹ of 2022 (level of ladders and panels)

Alignment - trends



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- Blue: High Granularity alignment for remaining 30 fb⁻¹ of 2022 (level of ladders and panels)
- Good stability of trends after deploying automated alignment
- Comparable physics performance achieved by the automated alignment

Pixel Cluster properties - Charge & size



- Trend of on-track cluster charge (left) and size (right) in BPix
- Trend shows degradation of performance due to radiation esp in the BPix L1 which is ~ 3 cm away from beam-pipe
 - To cope with irradiation, the HV of L1 was raised after which a recovery can be seen
 - Effects of beneficial annealing during technical stops are also seen.
- Regular bias scans are done during data taking to determine the best operating point of the detectors in various layers (more crucial for Layer 1).

Cluster properties - Bias scans



- Several Bias scans performed throughout the year
- Plots show the results of bias scans performed after an integrated lumi of 42 /fb during Run 3
- Current operating points
 - \circ $\,$ BPix: 400 V in Layer 1, 300 V in Layer 2 and 250 V in Layer 3 & 4 $\,$
 - \circ ~ FPix: 350 V in Ring 1 and 300 V in Ring 2 ~

Hit resolution



• The strip hit resolution is computed by using hits in overlapping modules of the same layer ("pair method").